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**HIGHWAY 285 TECHCONNECT CLUB** 

**TECHFEST** 

NOVEMBER 3, 2018

#### PROJECT GOALS

- Simple receiver design with readily available parts
- Adequate specifications for general use
- At home fabrication techniques
- Simple reconfiguration for the Arduino Controller and LCD Display Layout
- 50 ohm Interstage coupling for easy testing of each stage

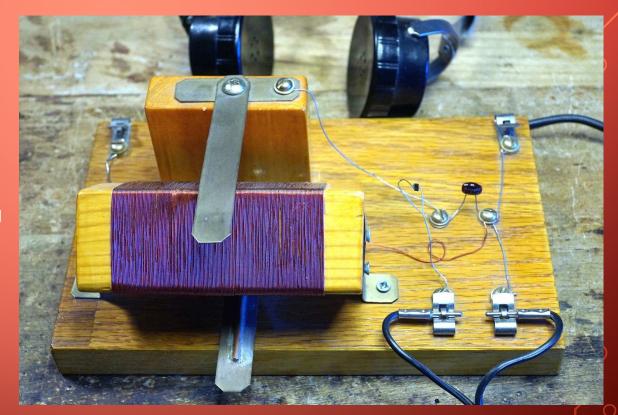
#### WILL FOCUS ON THE FOLLOWING TOPICS

- History
- Block Diagram and Overview
- General Specifications
- LO Frequency Selection
- I.F. Crystal Filter Design
- Microprocessor Controlled (ATMEGA 328)
  - Arduino Based Development System
- 7 inch Color LCD Touch Display
  - 4D Systems IDE for display configuration
- At home PCB fabrication
- Single Sided PCB, Maximize Ground Plane

- Rotarty Encoder Tuning Knob with selectable increments
- Variable Lowpass Audio Filter
- Two Local Oscillator DDS synthesizers
- Solid state front end switching
- Band Spectrum Display
- 10 User Memories
- Simulated Analog S Meter
- Externally programmable through a serial port
- 50 ohm Interstage coupling impedance
- Passband Offset Tuning

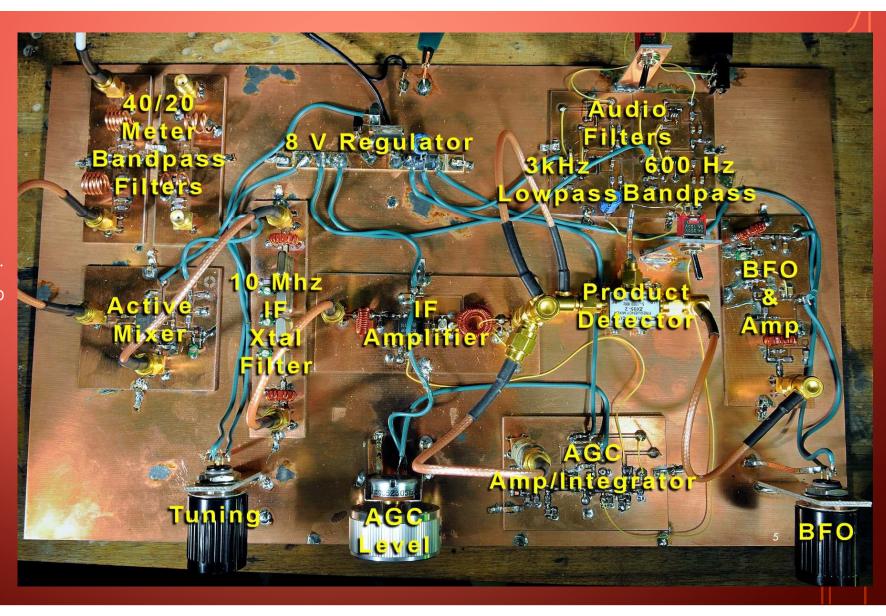
## **HISTORY**

- First Receiver Foxhole Radio
  - Razor Blade as a crystal detector
  - Of course, 110 turns on a toilet paper roll
- Second Receiver Dual Slide Tuning
  - 5<sup>th</sup> Grade
  - 11 years old



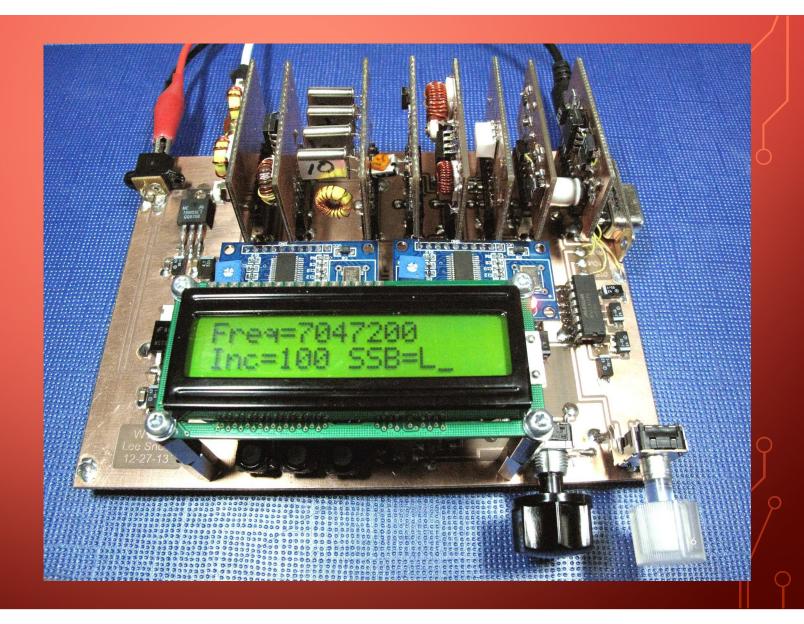
#### **HISTORY**

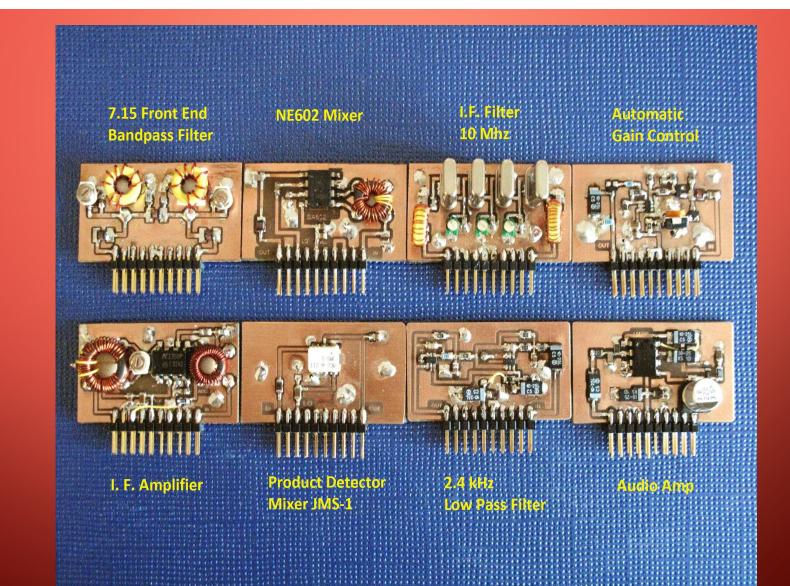
MY FIRST MODULAR RECEIVER BREADBOARD. EACH MODULE IS ON IT'S OWN PCB WITH 50 OHMS IN AND OUT



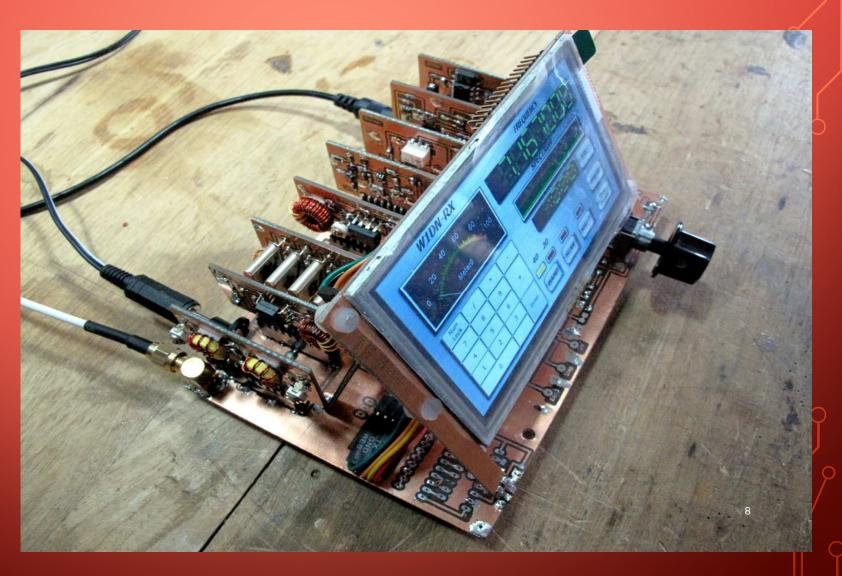
## **HISTORY**

SECOND RECEIVER
USING INDIVIDUAL
PLUG IN MODULES
AND A LCD DISPLAY

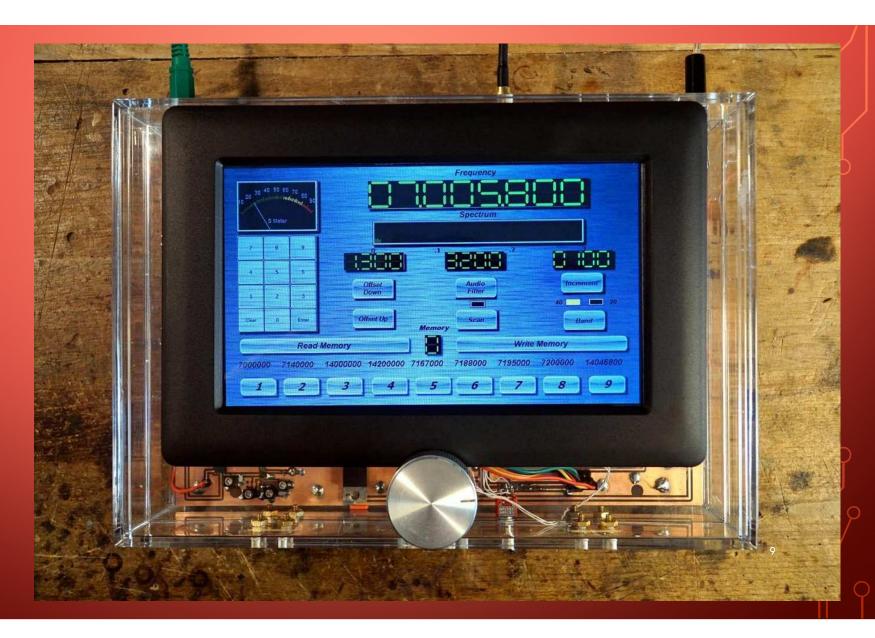




HISTORY
ITERATION WITH
4D SYSTEMS
COLOR TOUCH 4
INCH DISPLAY

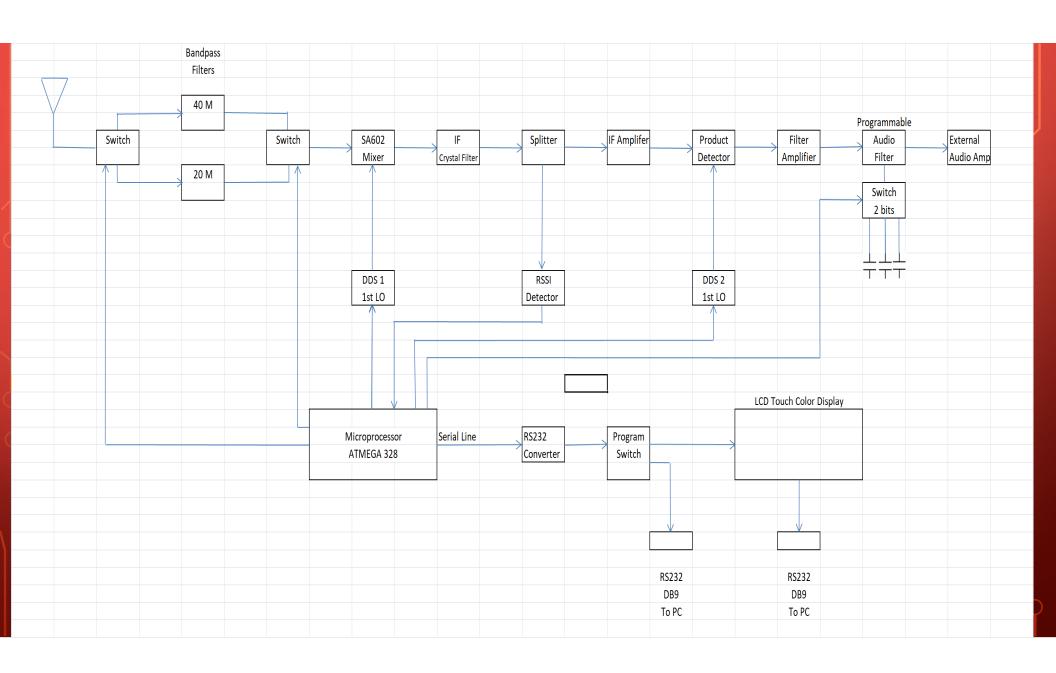


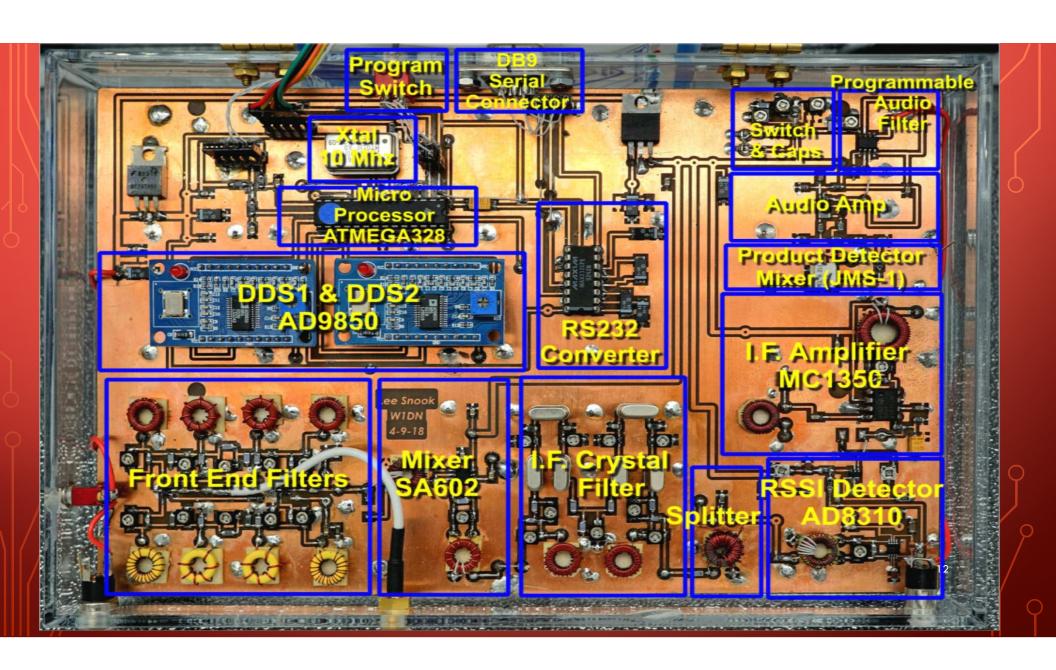
# HISTORY FOURTH RECEIVER (TODAY)





Internal view





#### GENERAL SPECIFICATIONS

• • •	• •
ensitiv	VITV
113111	V 11 7

• IMD

Third Order Intercept

• SFDR

$$-120 \text{ dBm } BW = 3200 \text{ Hz}$$

-42 dBm

$$((120-42)/2+42 = -3 \text{ dBm})$$

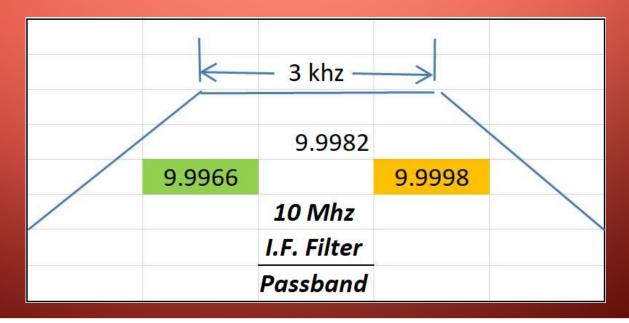
$$120-42 = 92 \text{ dbm}$$

#### LOCAL AND PRODUCT DETECTOR FREQUENCY SELECTION TABLE

Select a Local oscillator (LO) such that:

(use the lower cutoff edge since it has the steepest shape factor)

- As the receive frequency increase, the LO increases
- For LSB and USB the sideband falls within the crystal filter passband



#### 40 METERS

#### **RECEIVE 7 MHZ**

 $1^{ST}$  LO=16.9966 Mhz I.F. = 16.9966 – 7 = 9.996598 MHZ NOTE; THE LOWER EDGE OF THE I.F. CRYSTAL FILTER

#### • <u>Case 1</u>

- As the receive frequency increases
- the LO frequency increases
- LO = IF + RF

#### • Case 2 (For LSB)

- As the Receive Lower Sideband Envelope decreases
- the IF increases
- IF = LO RF

#### 20 METERS

#### **RECEIVE 14 MHZ**

1<sup>ST</sup> LO=4.003402 Mhz

$$IF = RF - LO$$

#### • <u>Case 1</u>

- As the receive frequency increases
- the LO frequency increases
- LO = IF + RF

#### • Case 2 (For LSB)

- the Receive Lower Sideband Envelope decreases
- the IF increases
- IF = LO RF

## **EXAMPLES (CONT.)**

#### **RECEIVE 14 MHZ**

1<sup>ST</sup> LO=4.003402 MHZ I.F. = 14-4.003402= 9.996598 MHZ NOTE; THE LOWER EDGE OF THE I.F. CRYSTAL FILTER

- <u>Case 1</u>; As the receive frequency increase, the LO frequency increases
- Receive 14.1 Mhz
- 1st LO=4.003402 Mhz
- I.F. = 14.1 4.003402 = 10.096598 Mhz Note; The Lower Edge of the I.F. Crystal Filter

- <u>Case 2</u>; For LSB, the Receive Lower Sideband Envelope decreases, the IF increases
- Receive 6.999 Mhz, 1 khz audio tone
- 1st LO=16.9966 Mhz
- I.F. = 16.9966 6.999 = 9.9976 Mhz
   Note; The LSB envelope is within the passband

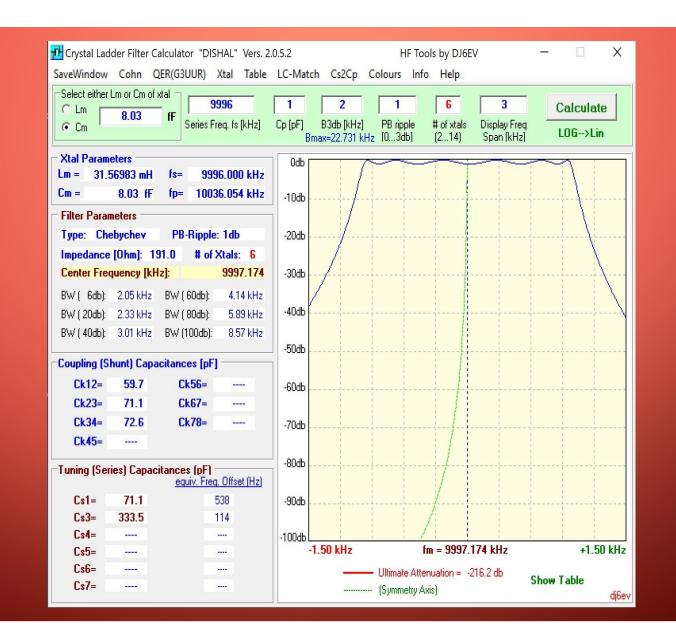
## CRYSTAL FILTER DESIGN

MEASURE A GROUP OF 10 MHZ CRYSTALS AND SELECT 6 THAT HAVE THE CLOSEST PARAMETERS

					Minus 45	45	Plus 45			
Xtal	RL	Loss in dB	Rm	Reff	fs	fl	fu	deltal f	Cm	Lm
11	12.5	2.62	8.801814	33.80181	9995949	9996160	9996332	172	8.10925E-15	0.03129334
12	12.5	2.37	7.842787	32.84279	9995918	9996130	9996297	167	8.10348E-15	0.031315828
18	12.5	2.49	8.299676	33.29968	9995912	9996126	9996289	163	7.80087E-15	0.032530651
22	12.5	2.97	10.19168	35.19168	9995893	9996113	9996292	179	8.10607E-15	0.031305982
Average:			fl	fc	fh	9996132			8.02992E-15	0.03161145
			9996215	9997815	9999415					

#### CRYSTAL FILTER DESIGN (CONT.)

- For a review of Crystal Filter Design use the following reference Crystal Motional Parameters, A Comparison of Measurement Approaches Jack R. Smith K8ZOA, 11 June 2006
- Using the Freeware Progam; DISHAL vers 2.0.5.2;
   Enter Lm, Cm, Cp, BW, # of Xtals, Ripple



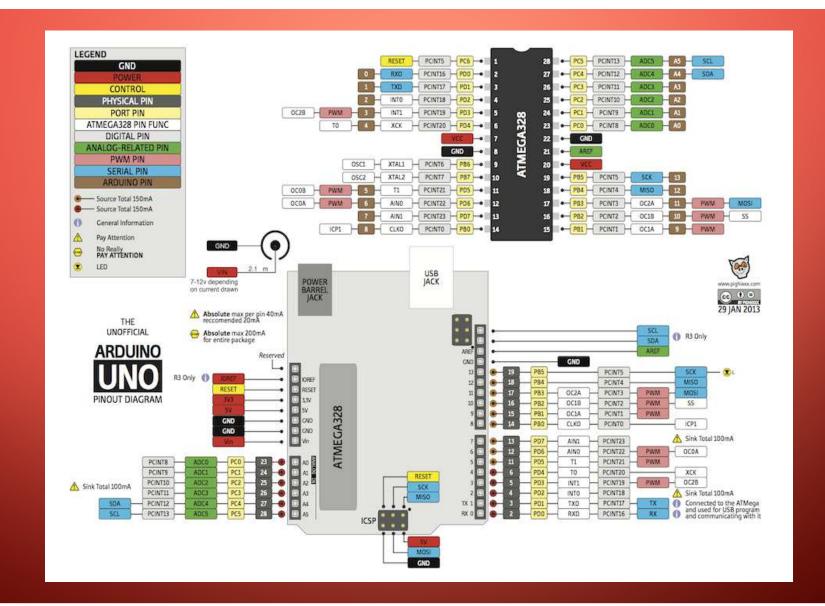
#### MEASURED RESULT

BANDWITH FOR THIS FILTER = 3 kHz



## **MICROPROCESSOR (ATMEGA 328)**

- The Arduino Uno prototyping board
- Arduino Uno is a microcontroller board based on the ATmega328Plt has 14 digital input/output pins (of which 6 can be used as PWM outputs), 6 analog inputs, a 16 MHz quartz crystal, a USB connection, a power jack, an ICSP header and a reset button. It contains everything needed to support the microcontroller; simply connect it to a computer with a USB cable or power it with a AC-to-DC adapter or battery to get started.
- Off-Boarding the ATMEG328 requires changing the pin assignments
- For instance; Programming a command to Pin 13 on the Uno Prototype board must now be changed to Pin19 for the stand alone ATMEGA328. See the diagame below.



#### MICROPROCESSOR PROGRAMMING

- Programming either the Uno board or the stand alone processor requires connecting a serial USB cable to the Uno USB port or, for the stand alone case, using a MAX232 chip to convert the RS232 voltages to 5 volts.
- I use an USB to RS232 converter cable which can be purchased online at;

https://www.amazon.com/Serial-RS232-Converter-Laptop-Notebook/dp/B00404P0L6

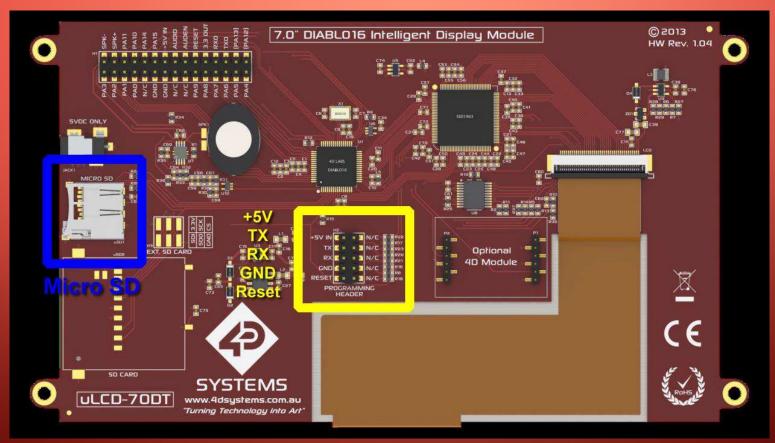
## MICROPROCESSOR PROGRAMMING (CONT.)

- A simple programming example:
- Make an LED blink. Connect and LED to Pin 13 of the Arduino Uno Proto board with the appropriate series dropping resistor of 330 ohms.
- Note: The maximum current sourcing pin current is = 40 ma.
- An integrated development environment (IDE) is a software application that ides comprehensive facilities to computer programmers for software development.
- Download the Arduino IDE at https://www.arduino.cc/en/Main/Software

```
Code:
// The setup function runs when you press reset or power the board
//Code in the setup(), Intitalizes Pins as Input or Output.
//Setup only runs Once on startup
// The void keyword is used only in function declarations. It indicates that the function is expected to return
no information
to the function from which it was called.
//The following code is for the UNO proto board, Pin 13 would be changed to pin 19 for the off boarded
processor.
void setup()
pinMode(Pin 13, OUTPUT); // initialize digital pin 13 as an output.
void loop()
                  // The loop function runs over and over again forever
digitalWrite(Pin 13, HIGH); // turn the LED on (HIGH is the voltage level)
                              // wait for a second
delay(500);
digitalWrite(Pin 13, LOW); // turn the LED off by making the voltage LOW
                             // wait for a second
delay(500);
```

## PROGRAMMING THE 4D SYSTEMS LCD DISPLAY

Backside view



- The microUSB Programming Adaptor (uUSB-PA5 and uUSB-PA5-II) is a USB to Serial-TTL UART bridge converter
- Insert the micro SD card into the PC USB port (use micro to mini USB adapter card if necessary)
- Connect uUSB-PA5 from +5V, TX, RX,
   GND, Reset connector to PC USB port.



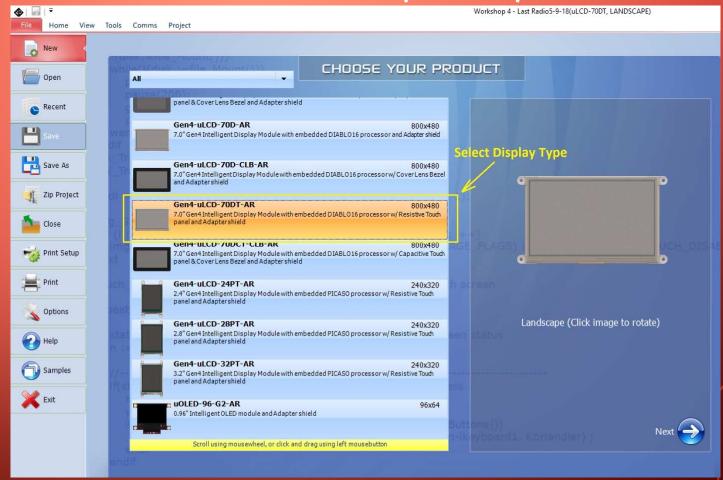


#### PROGRAMMING THE LCD DISPLAY

Boot up the IDE program



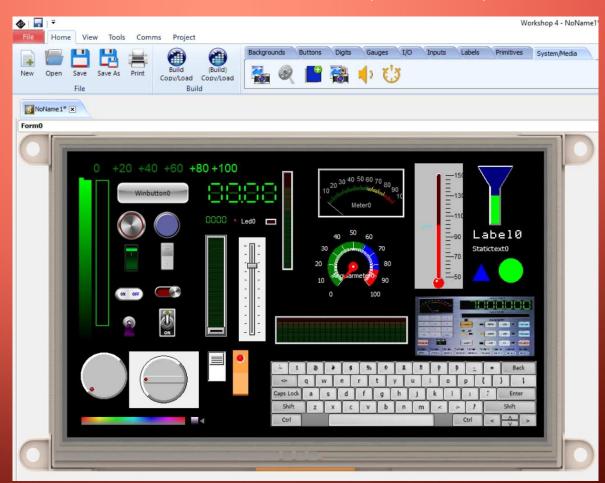
Select the ViSi Genie Display Type and Orientation



Environment;
By simply laying the display out with the wanted objects and setting the events to drive them, the code is written automatically. ViSi-Genie provides the latest rapid development experience from 4D Labs



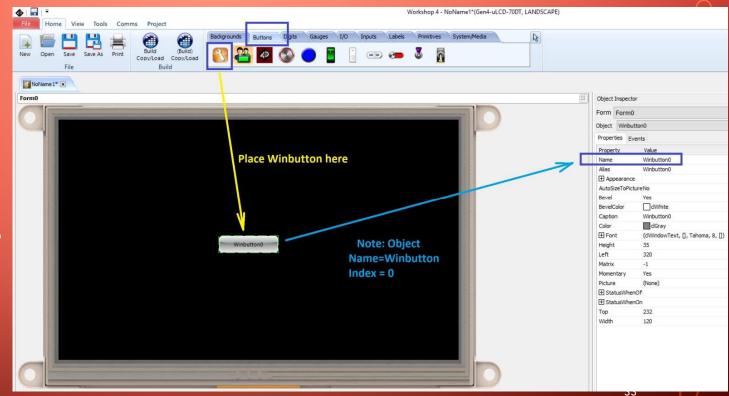
Control Objects that can be used



Start the LCD layout by selecting and placing the "Objects" onto the workspace.

Example: In this example we will place a Button on the screen and note the Object Inspector Remember to Select the Comms Tab and Comm Port, it will turn Blue when connected.

Name and Index number.



Under Object
Inspector on the right side of the screen, select the Events Tab and select "Report Message".



#### **EVENT HANDLER EXAMPLE**

The Arduino Code (in the Event Handler) will look for a Winbutton Event with an Index of O and execute the user code when this button is pressed.

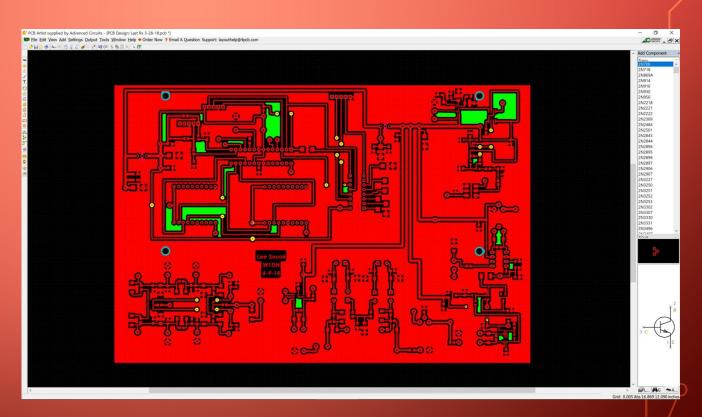
The programming language used for Arduino is based on  $\bf C$  language. The syntax is almost identical to that of  $\bf C$  or  $\bf C++$ .

## **EVENT HANDLER EXAMPLE (CONT.)**

```
Void Loop()
genie.DoEvents();
void myGenieEventHandler(void)
  genieFrame Event;
  genie.DequeueEvent(&Event);
 if(Event.reportObject.cmd == GENIE_REPORT_EVENT)
  if (Event.reportObject.object == GENIE_OBJ_WINBUTTON)
    //-----If Winbutton Pressed, Do Something-----
       if (Event.reportObject.index == 0)
                                    // If Button(0)
                 //Do Something
```

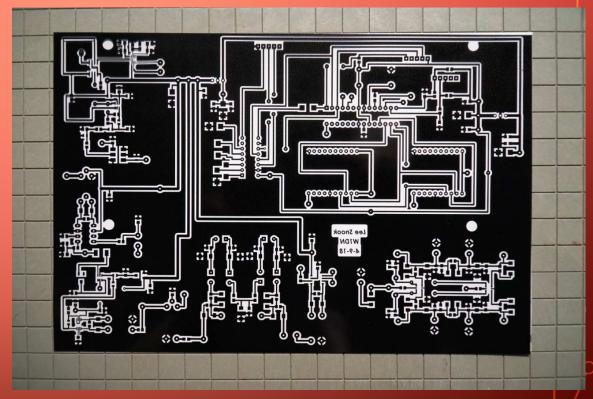
### PCB FABRICATION PROCESS

I use PCB Artist for Schematic Capture and Board Layout

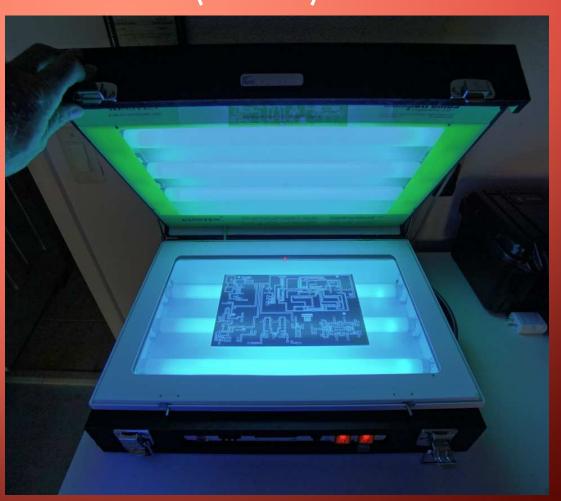


The Receiver Layout in PCB Artist:

- Using an Ink Jet printer,
  - print the Top Copper side of the Layout
  - High Contrast Black
  - onto rough side of transparent film
- Remember, under printer settings, Flip the print under the printer setup so that the rough side is facing the photo sensitive side of the PCD board.

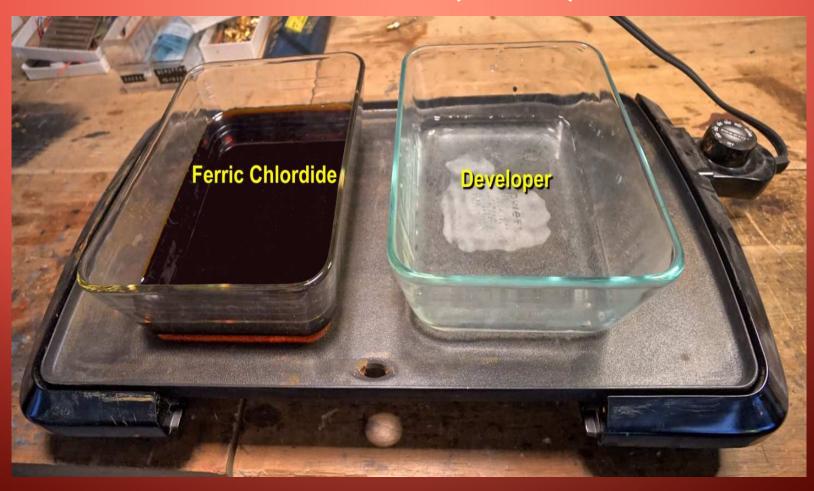


- Remove the light protective film from the photo sensitive PCB board
- Insert the photo sensitive board under the transparent film and expose in a lightbox



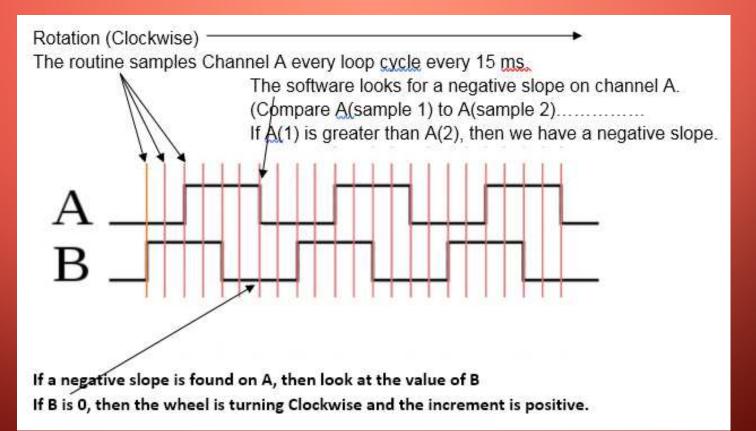
- Heat Developer and Ferric Chloride to ~90 degrees F.
- Exposed PCB into glass tray with PCB Developer
  - DATAK Cat. No 12-404 Positive Type PCB Developer
  - Developer concentrate diluted 1:10 with water.
- Agitate until the Light Sensitive Film (Green color) is dissolved between traces.
- Wash the board

- Board into Ferric Chloride Etchant Solution bath
  - MG Chemicals #415-1L,945 ml bottles Ferric Chloride
  - Typically 15 minutes
- Periodically agitate
- Inspect and remove when the copper between traces has been dissolved
- Wash off Ferric Chloride with fresh water

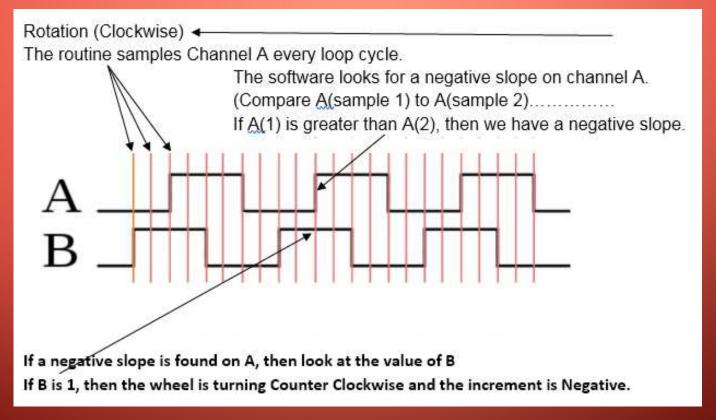


#### QUADRATURE ROTARY ENCODER

SPARKFUN ELECTRONICS; PN COM-11102



## **QUADRATURE ROTARY ENCODER (CONT.)**



An RC time network was added to Ports A and B for Debounce. R=10k and C=.01 µf.

## Quadrature Rotary Encoder (cont.)

```
In the following code;

A1=Sample 1 of Port A

A2=Sample 2 of Port A

B=Sample Port B

//-----Rotarty Encoder------

A1=digitalRead(Encoder_Pin1);
delay(15); //Delay next sample by

15 ms

A2=digitalRead (Encoder_Pin1);
B=digitalRead(Encoder_Pin2);
```

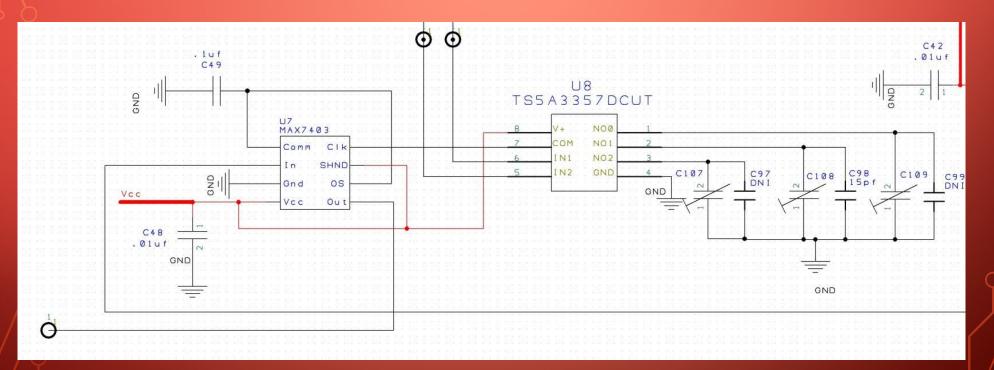
```
if (A1>A2)
                                   //A1(sample 1) is greater
than A2(sample 2)
     if (B==HIGH)
      f_rx=f_rx+increment[inc_pointer]; //Increase frequency
by increment
      freq_low=(f_rx%10000);
      freq_high=(f_rx-freq_low)/10000;
      genie.WriteObject(GENIE_OBJ_LED_DIGITS, 2, freq_low);
      genie.WriteObject(GENIE_OBJ_LED_DIGITS, 3, freq_high);
      load1();
     else
                                   //A(sample 1) is less than
A(sample 2)
      f_rx=f_rx-increment[inc_pointer];
                                        //Decrease frequency
by increment
      freq_low=(f_rx%10000);
      freq_high=(f_rx-freq_low)/10000;
      genie.WriteObject(GENIE_OBJ_LED_DIGITS, 2, freq_low);
      genie.WriteObject(GENIE_OBJ_LED_DIGITS, 3, freq_high);
      load1();
```

More work is required, sometimes the encoder will skip a count when turning the wheel too fast.

#### VARIABLE BANDPASS AUDIO FILTER

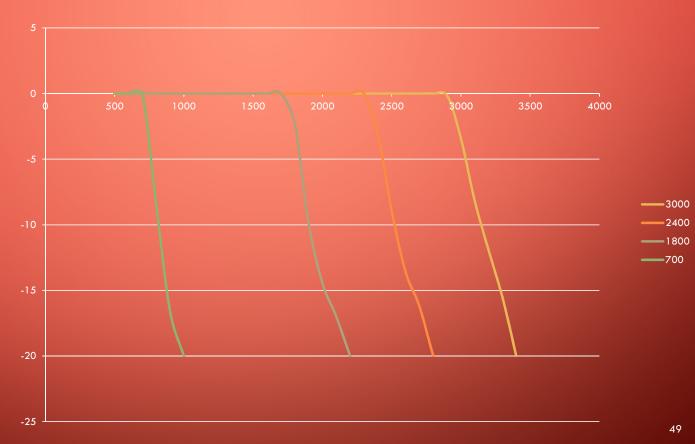
- MAX7403 is a 8th-order, lowpass, elliptic, switched-capacitor filters
- These devices draw 2mA of supply current and allow corner frequencies from 1Hz to 10kHz
- Two clocking options are available
  - self-clocking through the use of an external capacitor
  - external clocking for tighter cutoff-frequency control
- Cutoff Frequency=Clock/100. Fosc(kHz)=(38\*10000)/Cosc; Cosc is in pf.
- For my application, I used external capacitors (self clocking) switched with a solid state single pole three throw switch (TS5A3357)

# VARIABLE BANDPASS AUDIO FILTER (CONT.)



## **VARIABLE BANDPASS AUDIO FILTER (CONT.)**

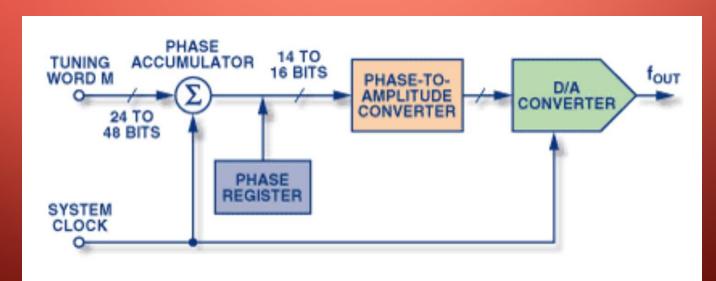
Audio Lowpass
 Filter Frequency
 Response



# DDS (DIRECT DIGITAL SYNTHESIZERS (AD9850) DDS TUTORIAL

- Traditional designs of high bandwidth frequency synthesizers employ the use of a phase-locked-loop (PLL).
- A direct digital synthesizer (DDS) provides many significant advantages over the PLL approaches
  - Fast settling time
  - Sub-Hertz frequency resolution
  - Continuous-phase switching response
  - Low phase noise

- A DDS produces a sine wave at a given frequency
- The frequency depends on two variables
  - Reference-clock frequency
  - Binary number programmed into the frequency register (tuning word)



- Binary number in frequency register provides main input to phase accumulator
- Sine look-up table used
- Phase accumulator computes phase (angle) address for look-up table
  - Outputs the digital value of amplitude
  - Crresponding to the sine of that phase angle—to DAC
- DAC converts number to a corresponding value of analog voltage or current

- To generate a fixed-frequency sine wave, constant value (the phase increment
  - from binary number added to the phase accumulator with each clock cycle.
    - If the phase increment is large, the phase accumulator will step quickly through the sine look-up table and thus generate a high frequency sine wave.
    - If the phase increment is small, the phase accumulator will take many more steps,

accordingly generating a slower waveform

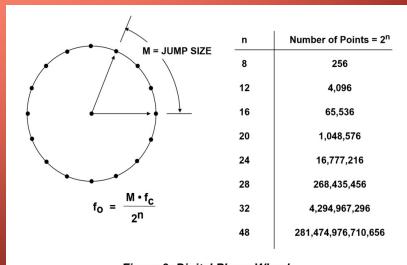
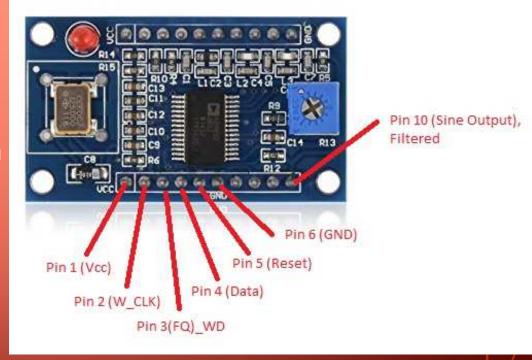


Figure 3: Digital Phase Wheel

- Consider the case for n = 32, and M = 1. The phase accumulator steps through each of 232 possible outputs before it overflows and restarts. The corresponding output sinewave frequency is equal to the input clock frequency divided by  $2^32$ . If M=2, then the phase accumulator register "rolls over" twice as fast, and the output frequency is doubled. This can be generalized as follows.
- For an n-bit phase accumulator (n generally ranges from 24 to 32 in most DDS systems), there are 2n possible phase points. The digital word in the delta phase register, M, represents the amount the phase accumulator is incremented each clock cycle. If fc is the clock frequency, then the frequency of the output sinewave is equal to:
- $fOUT = (\Delta \ Phase \times CLKIN)/2^{32}$
- Δ Phase=( fOUT ×2<sup>32</sup>)/ CLKIN

#### **DIRECT DIGITAL SYNTHESIZERS**

- AD9850 is a highly integrated device that uses advanced DDS technology coupled with an internal high speed, high performance D/A converter and comparator to form a complete, digitally programmable frequency synthesizer and clock generator function.
- Premounted on a small PCB online from either Amazon or Digikey.



## **DIRECT DIGITAL SYNTHESIZER (AD9850)**

- The frequency tuning, control, and phase modulation words are loaded into the AD9850 via
  - Parallel byte or
  - Serial loading format (I used the serial loading format)
- In serial load mode, subsequent rising edges of W\_CLK shift the 1-bit data on Pin 25 (D7) through the 40 bits of programming information.
- After 40 bits are shifted through, an FQ\_UD pulse is required to update the output frequency (or phase).

```
The Arduino Code for loading the DDS synthesizer:
//----DDS Loader---
long function delta phase1()
 freq dds1=f rx+if center-offset;
//From the equation above \triangle Phase=( fOUT ×2<sup>32</sup>)/ CLKIN
 long delta phase1 =(((freq dds1)*pow(2,32))/clock);
return (delta_phase1);
void load1()
 long delta phase1=function delta phase1();
 digitalWrite (LOAD1 Pin, LOW);
 shiftOut(DATA Pin, CLOCK Pin, LSBFIRST, delta phase1);
 shiftOut(DATA Pin, CLOCK Pin, LSBFIRST, delta phase1 >>
8);
 shiftOut(DATA Pin, CLOCK Pin, LSBFIRST, delta phase1 >>
16):
 shiftOut(DATA Pin, CLOCK Pin, LSBFIRST, delta phase1 >>
24);
 shiftOut(DATA Pin, CLOCK Pin, LSBFIRST, 0x0);
 digitalWrite (LOAD1 Pin, HIGH);
```